



Electronics – 96032

 POLITECNICO DI MILANO



Loop Compensation

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Disclaimer

Slides are supplementary
material and are NOT a
replacement for textbooks
and/or lecture notes

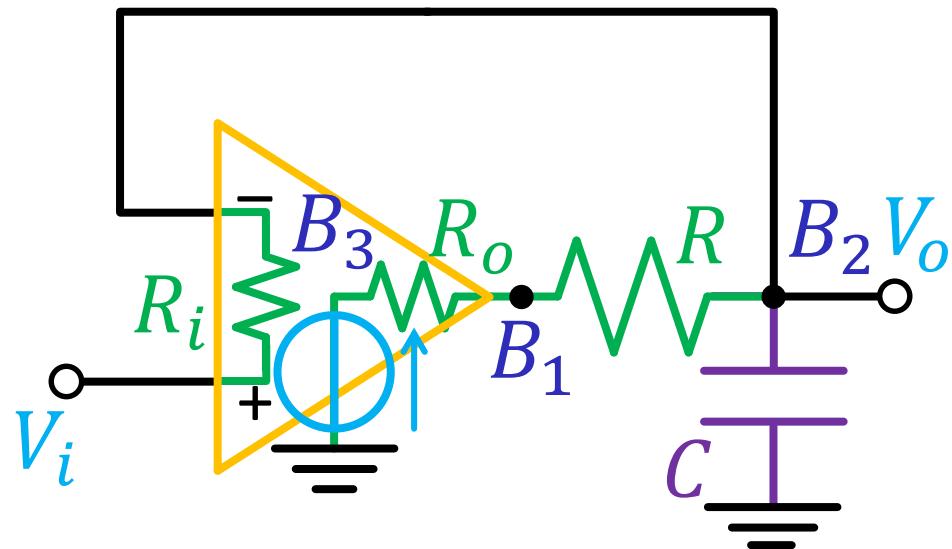
Outline

- Impedance reconstruction
- Compensation
- Appendix: poles and zeros of a network

Breaking the loop

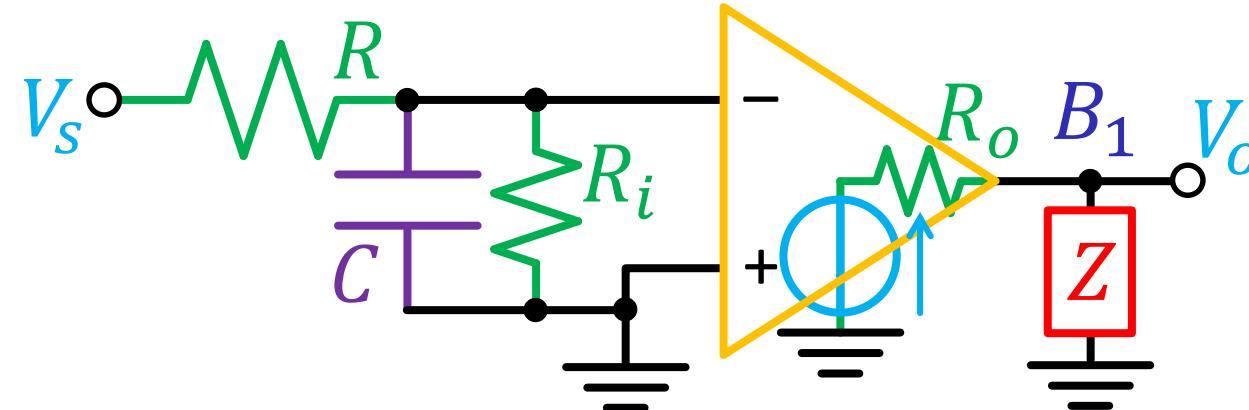
- In a block scheme, it makes no difference where you choose to break the loop
- In a real circuit, you must terminate the loop end with the impedance that existed before you broke the loop
- In reality, things are even more complex because you must be careful not to modify the DC operating point

Example: buffer stage



- $R = 900 \Omega, C = 20 \text{ nF}$
 - $R_i = 1 \text{ M}\Omega, R_o = 10 \Omega$
 - $GBWP = 1 \text{ MHz}, A_0 = 100 \text{ dB}$
1. Evaluate the loop gain using B_1, B_2 and B_3 as breakpoints
 2. Compensate if needed
(neglect R_i for simplicity)

Loop breaking – case B₁

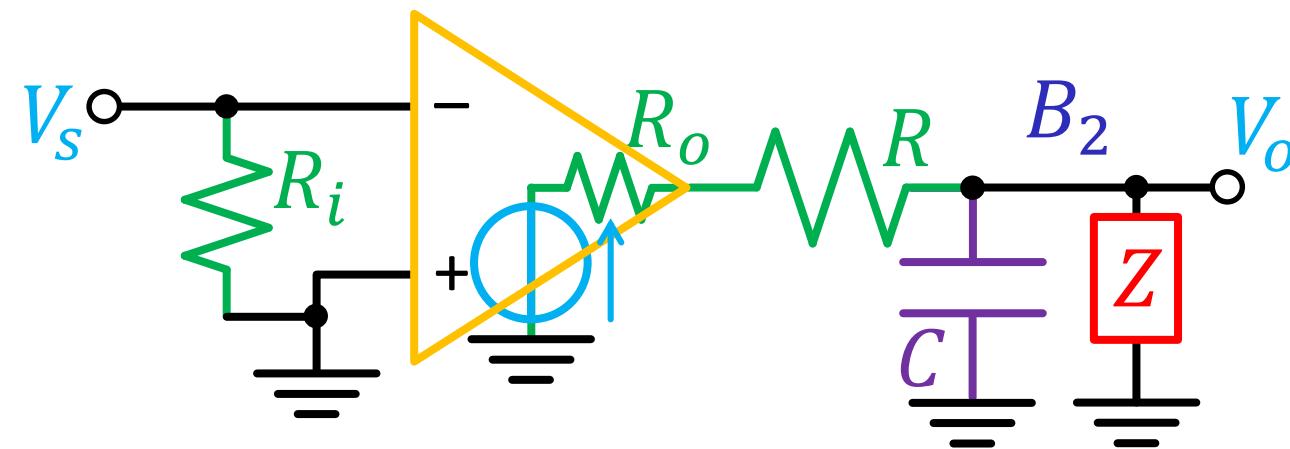


$$Z = \frac{R}{sC + R_i} = R + \frac{1}{sC} \parallel R_i = (R + R_i) \frac{1 + sC(R \parallel R_i)}{1 + sCR_i}$$

Calculations – case B₁

$$G_{loop}^1 = - \frac{\frac{1}{sC} \parallel R_i}{R + \frac{1}{sC} \parallel R_i} A(s) \frac{Z}{Z + R_o} = -A(s) \frac{\frac{1}{sC} \parallel R_i}{R + R_o + \frac{1}{sC} \parallel R_i}$$

Loop breaking – case B₂

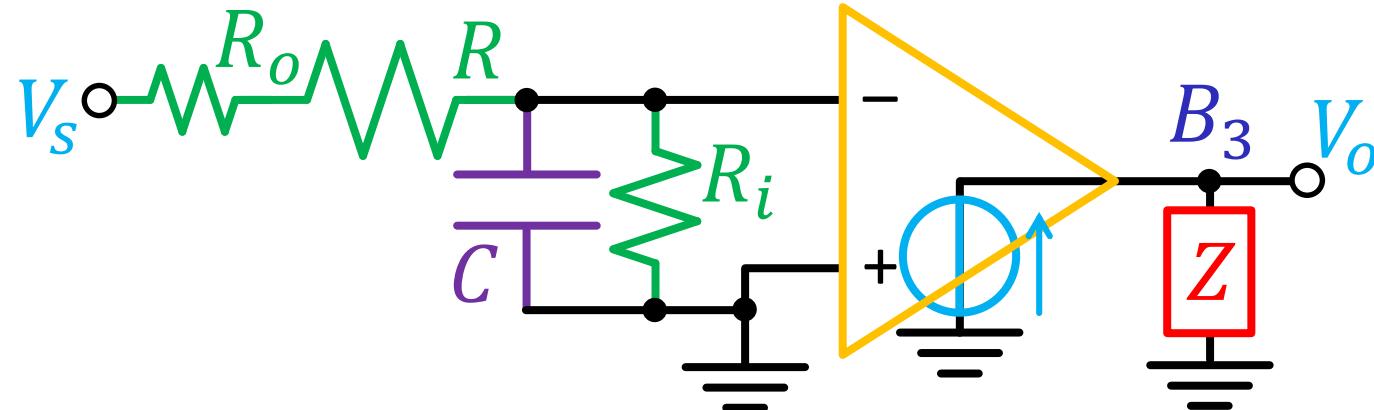


$$Z = R_i$$

Calculations – case B₂

$$G_{loop}^2 = -A(s) \frac{\frac{1}{sC} \parallel Z}{R + R_o + \frac{1}{sC} \parallel Z} = -A(s) \frac{\frac{1}{sC} \parallel R_i}{R + R_o + \frac{1}{sC} \parallel R_i}$$

Loop breaking – case B₃



$$Z = \frac{R_o + R}{R_i} = R + R_o + \frac{1}{sC} \parallel R_i$$

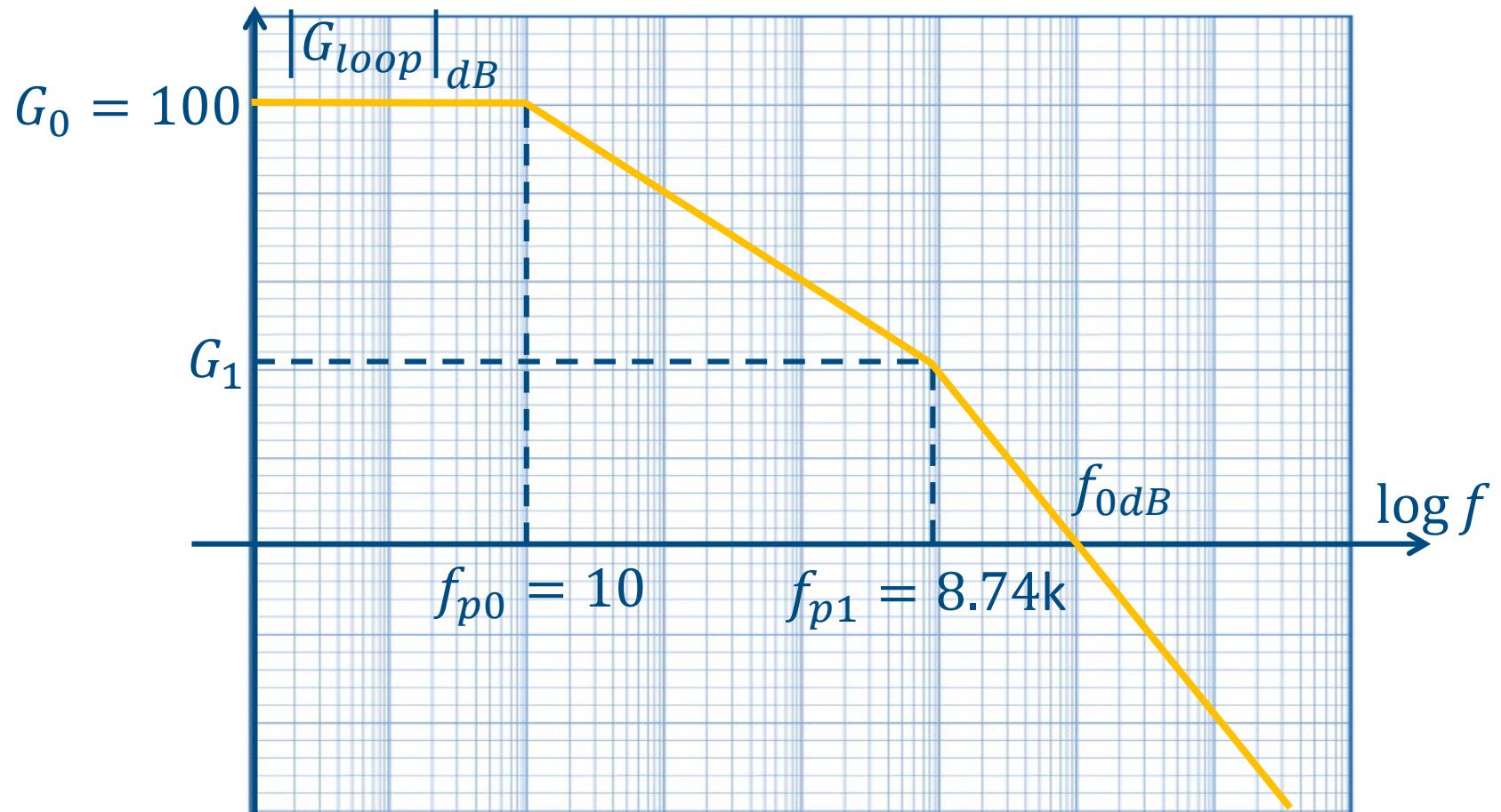
(but it is not needed
for the calculations!)

Calculations – case B₃

$$\begin{aligned}
 G_{loop}^3 &= -A(s) \frac{\frac{1}{sC} \parallel R_i}{R + R_o + \frac{1}{sC} \parallel R_i} \\
 &= -\frac{A_0}{1 + s\tau} \frac{R_i}{R + R_o + R_i} \frac{1}{1 + sC(R_i \parallel (R + R_o))} \\
 &\approx -\frac{A_0}{1 + s\tau} \frac{1}{1 + sC(R + R_o)}
 \end{aligned}$$

10 Hz 8.74 kHz

Bode plot



Phase margin

$$G_0 f_{p0} = G_1 f_{p1} \Rightarrow G_1 = G_0 \frac{f_{p0}}{f_{p1}} = 114 = 41 \text{ dB}$$

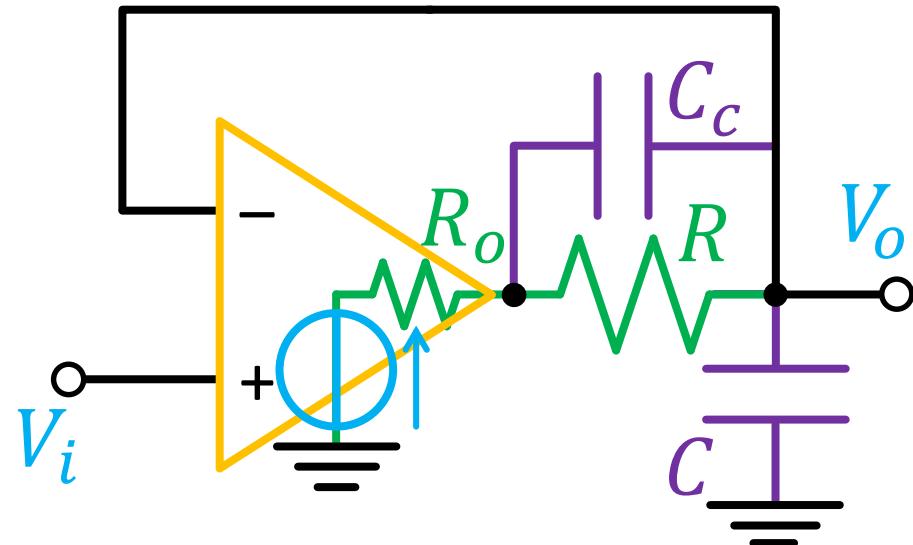
$$G_1 f_{p1}^2 = f_{0dB}^2 \Rightarrow f_{0dB} = f_{p1} \sqrt{G_1} = 93.2 \text{ kHz}$$

$$\phi_m = 180 - 90 - \arctan \left(\frac{f_{0dB}}{f_{p1}} \right) = 5^\circ$$

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Compensation (negl. R_i)



$$G_{loop} = -A(s) \frac{\frac{1}{sC}}{R_o + R \parallel \frac{1}{sC_c} + \frac{1}{sC}}$$

Effect of C_c

$$G_{loop} = -\frac{A_0}{1 + s\tau} \frac{1 + sC_cR}{1 + s(CR + CR_o + C_cR) + s^2CC_cRR_o}$$

1. A zero is introduced in G_{loop}
2. A second pole also arises
3. The poles time constants are entangled

Sizing of C_c – LF/HF approximation

- LF: $C_c = \text{open circuit}$. The pole is

$$f_{p1} = \frac{1}{2\pi C(R + R_o)} = 8.74 \text{ kHz},$$

obviously not affected by C_c . So f_{0dB} is still 93.2 kHz. To achieve a phase margin of 45° we then need $f_z = f_{0dB}$, i.e.

$$\frac{1}{2\pi C_c R} = 93.2 \times 10^3 \Rightarrow C_c = 1.88 \text{ nF}$$

- HF: $C = \text{short circuit}$. The pole is now

$$f_{p2} = \frac{1}{2\pi C_c(R \parallel R_o)} = 8.47 \text{ MHz}$$

Sizing of C_c – Analytical approximation

- Given a 2nd order polynomial with well-separate **real** roots (i.e., $\tau_1 \gg \tau_2$), we can write

$$(1 + s\tau_1)(1 + s\tau_2) = 1 + s(\tau_1 + \tau_2) + s^2\tau_1\tau_2 \approx 1 + s\tau_1 + s^2\tau_1\tau_2$$

- Approximate values of the roots are

$$as^2 + bs + 1 = 0 \Rightarrow \begin{aligned} s_{LF} &\approx -\frac{1}{b} \\ s_{HF} &\approx -\frac{b}{a} \end{aligned}$$

- The error is of the order of the ratio of the roots

Analytical approximation – caveat

- Consider the previous cases with $\tau_1 \gg \tau_2$:

$$s^2\tau_2\tau_1 + s\tau_1 + 1 = 0 \Rightarrow \begin{aligned} \omega_{LF} &\approx \frac{1}{\tau_1} & \omega_{LF} &\approx \frac{1}{\tau_2} \\ \omega_{HF} &\approx \frac{1}{\tau_2} & \omega_{HF} &\approx \frac{1}{\tau_1} \end{aligned}$$

- In the second case we have $\omega_{LF} \gg \omega_{HF}$, which is impossible \Rightarrow the solution is wrong and actual poles are complex!
- Always check the significance of your results!

Pole position

- Pole frequencies become:

- $f_{p1} = \frac{1}{2\pi(C(R+R_o)+C_cR)}$

- $f_{p2} = \frac{C(R+R_o)+C_cR}{2\pi C C_c R R_o}$

- Values are similar to the previous ones, if $C_c \ll C$. As an example, with the previous value $C_c = 1.88 \text{ nF}$ we get

$$f_{p1} = 8.0 \text{ kHz}; f_{p2} = 9.36 \text{ MHz}$$

Sizing of C_c - 2

$$\begin{cases} G_0 f_{p0} = G_1 f_{p1} \\ G_1 f_{p1}^2 = f_z^2 \end{cases} \Rightarrow f_z^2 = G_0 f_{p0} f_{p1}$$

$$\left(\frac{1}{C_c R}\right)^2 = \frac{A_0}{\tau(CR + CR_0 + C_c R)}$$

- If $C_c \ll C$ we can neglect the last term, obtaining $C_c = \sqrt{\tau(CR + CR_0)/A_0}/R = 1.88 \text{ nF}$ (same expression as before)
- The correct solution gives $C_c = 1.98 \text{ nF}$

Phase margin > 45°

- If – say – $\phi_m = 60^\circ$ is required, we have

$$\arctan\left(\frac{f_{0dB}}{f_z}\right) = 60^\circ \Rightarrow f_{0dB} = 1.73f_z$$

$$\begin{cases} G_1 f_{p1}^2 = G_z f_z^2 \\ G_z f_z = f_{0dB} \end{cases} \Rightarrow f_z^2 = \frac{G_0 f_p f_{p1}}{1.73}$$

- Result is $C_c \approx 2.5 \text{ nF}$

Homework

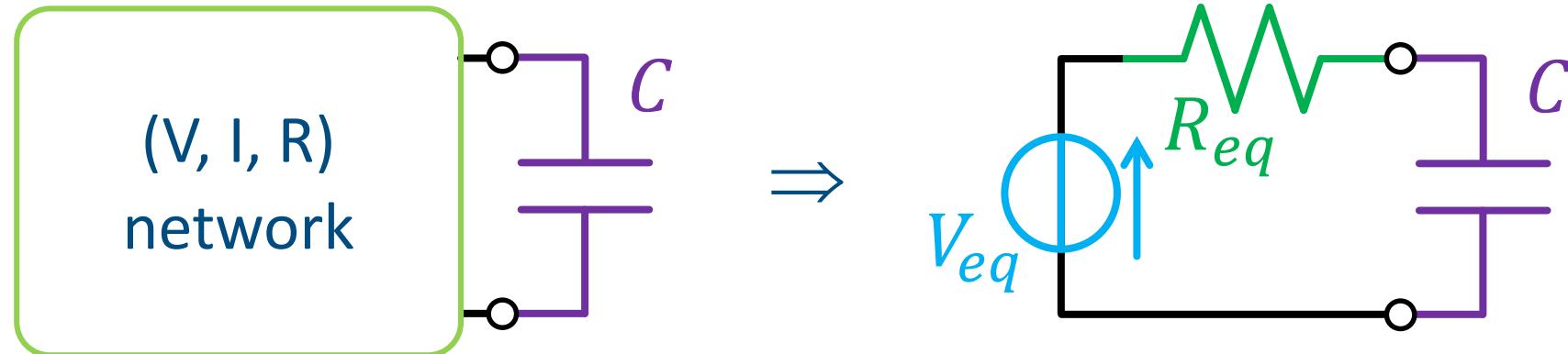
1. Compute the loop gain for the buffer stage (slide #5) using a **current source**
2. Compensate the buffer stage using a resistor rather than a capacitor

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Network pole

- We consider a generic network with only one reactive element (say, a capacitor)
- Thevenin theorem can be applied at the capacitor port:



- The time constant of the pole is CR_{eq} , where R_{eq} is the equivalent resistance seen at the capacitor port

Presence of a zero

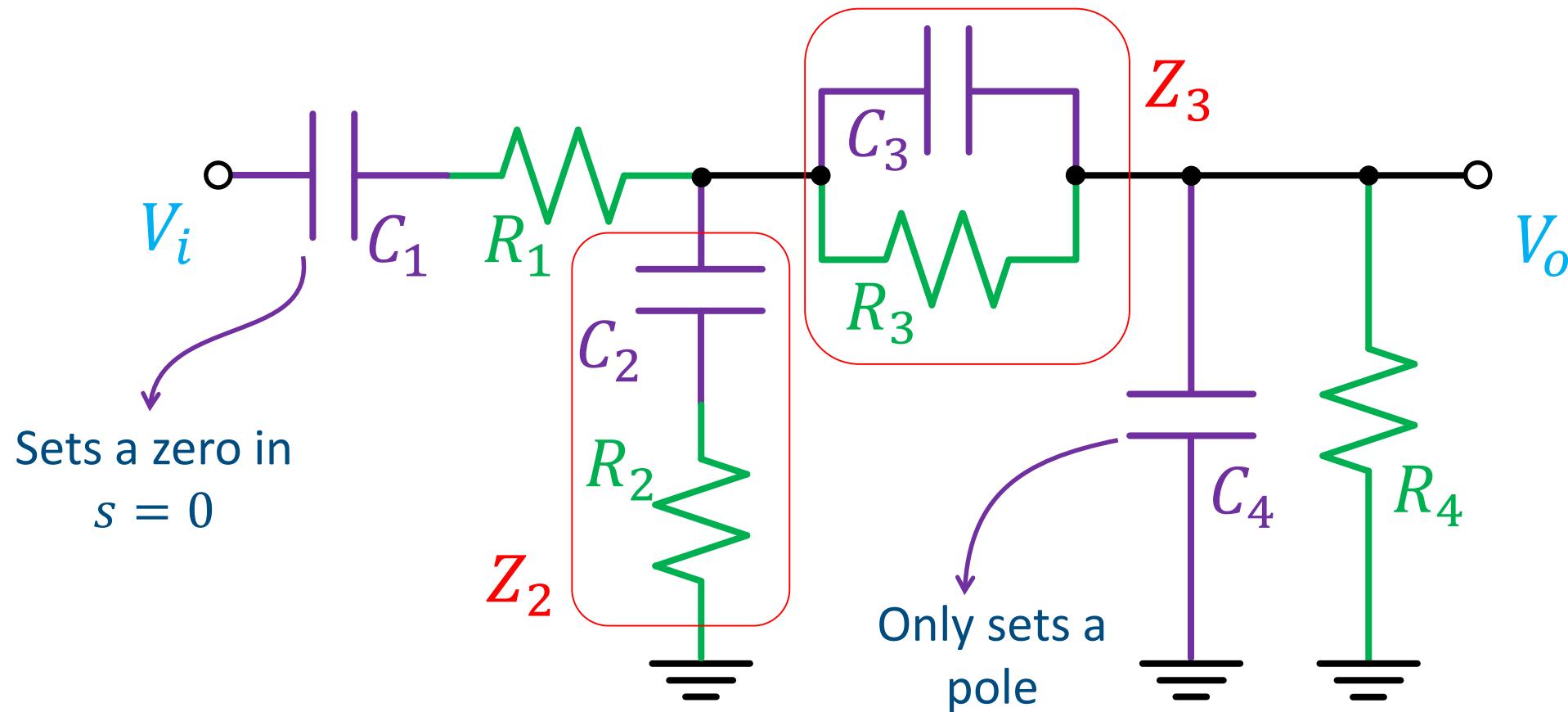
- A capacitor always adds a pole, but does not always add a zero to the transfer function
- To tell when this is the case, consider these two limits:

$$\lim_{s \rightarrow \infty} \frac{A}{1 + s\tau_p} = 0$$

$$\lim_{s \rightarrow \infty} A \frac{1 + s\tau_z}{1 + s\tau_p} \neq 0$$

- In practice: replace the capacitor with a short-circuit
 - If the output is null, there is only a pole
 - If the output is non-zero, there is a pole and a zero

Position of the zero: example



Evaluation

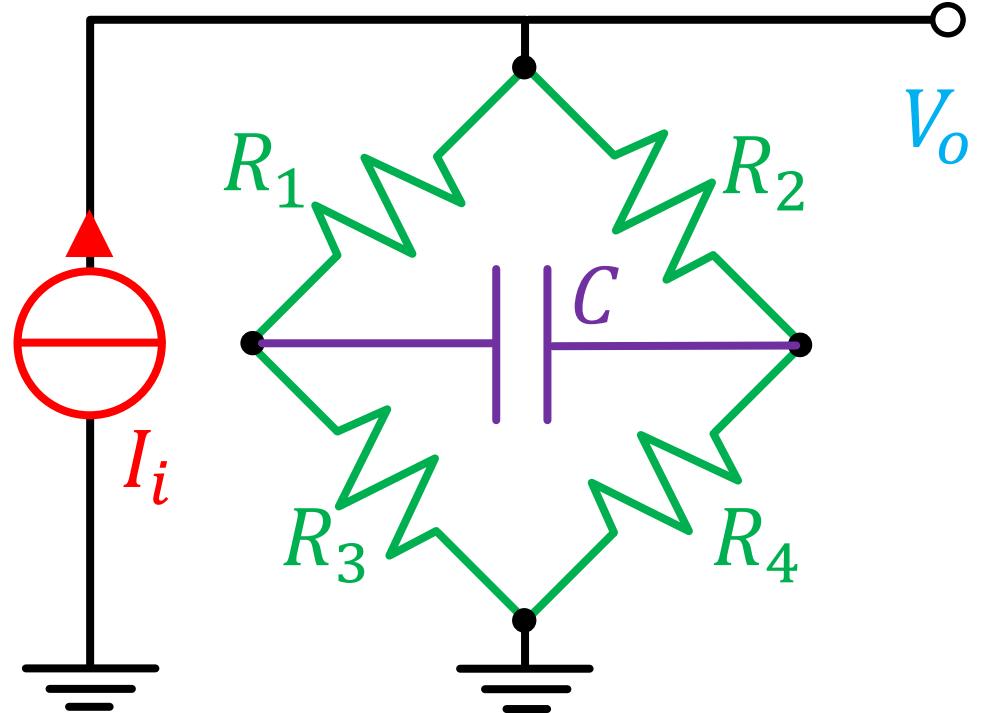
- If $Z_2(s) = 0$, the output is nulled and a zero arises

$$Z_2 = R_2 + \frac{1}{sC_2} = \frac{1 + sC_2R_2}{sC_2} = 0 \Rightarrow s = -\frac{1}{C_2R_2}$$

- If $Z_3(s) = \infty$, the output is nulled and a zero arises

$$Z_3 = R_3 \parallel \frac{1}{sC_3} = \frac{R_3}{1 + sC_3R_3} = \infty \Rightarrow s = -\frac{1}{C_3R_3}$$

However... not everything is straightforward



- The pole time constant is $\tau_p = C((R_1 + R_2) \parallel (R_3 + R_4))$
- $V_o(\infty) \neq 0 \Rightarrow C$ also adds a zero
- What is the time constant of the zero?

A possible approach

- The TF can be written as

$$H(s) = H(0) \frac{1 + s\tau_z}{1 + s\tau_p} \Rightarrow H(\infty) = H(0) \frac{\tau_z}{\tau_p} \Rightarrow \tau_z = \tau_p \frac{H(\infty)}{H(0)}$$

- In our case

$$H(0) = (R_1 + R_3) \parallel (R_2 + R_4) \quad H(\infty) = R_1 \parallel R_2 + R_3 \parallel R_4$$

$$\begin{aligned} \tau_z &= C((R_1 + R_2) \parallel (R_3 + R_4)) \frac{R_1 \parallel R_2 + R_3 \parallel R_4}{(R_1 + R_3) \parallel (R_2 + R_4)} = \\ &C(R_1 \parallel R_3 + R_2 \parallel R_4) \end{aligned}$$

Comment

- The last method works fine when the numerical value is needed (or in a Bode plot), but can return lengthy symbolic expressions
- A different technique, called the double null injection, can be used but is outside the scope of this class
- In these cases, it might be better to directly solve the circuit (other theorems are available)