

Electronics – 96032



POLITECNICO DI MILANO



# Amplifiers and Feedback Theory

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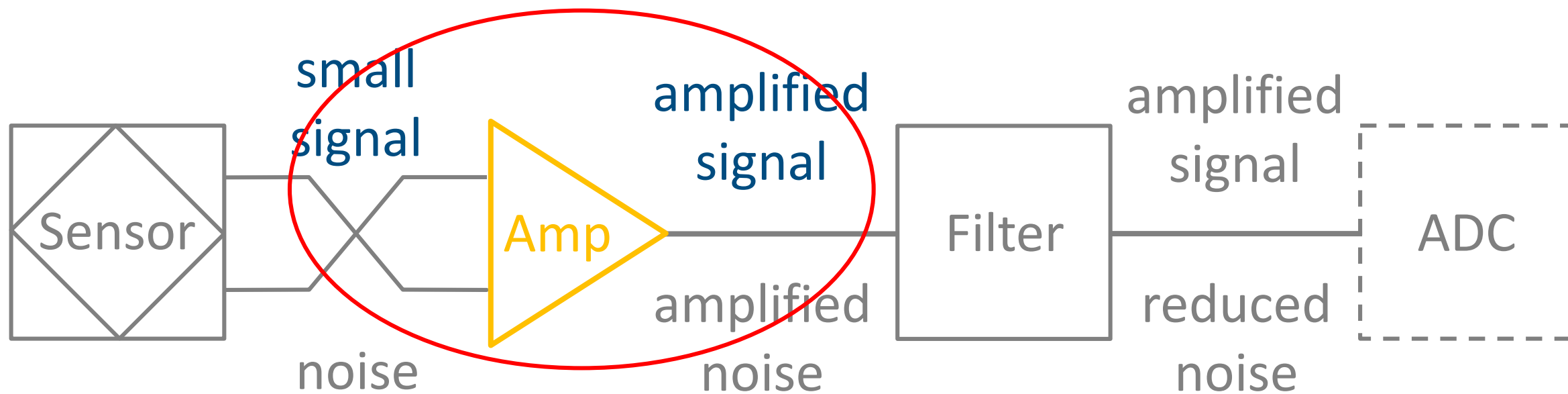


Slides are supplementary material and are NOT a replacement for textbooks and/or lecture notes



# Acquisition chain

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next lessons



# Purpose of the lesson

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- We begin our study with the analysis and design of simple amplifiers
- Next lessons will deal with
  - Basic amplifier principles and the feedback amplifier concept (this lesson)
  - Linear applications of OpAmps
  - Feedback amplifier properties
  - Stability of feedback amplifiers
  - Instrumentation amplifiers and OpAmp parameters



- Review: equivalent circuits
- Amplifiers
- Negative feedback
- Operational amplifiers



# The origin

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## Voltage source equivalent circuit



Hermann von  
Helmholtz  
(1821-1894)

1853



Lèon Charles  
Thévenin  
(1857-1926)

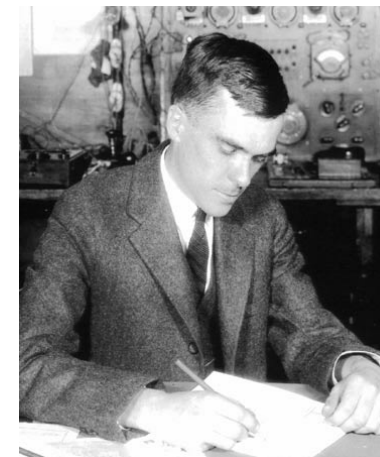
1883

## Current source equivalent circuit



Hans Ferdinand  
Mayer  
(1895-1980)

1926



Edward Lawry  
Norton  
(1898-1983)

1926

From [1]



# Equivalent circuits

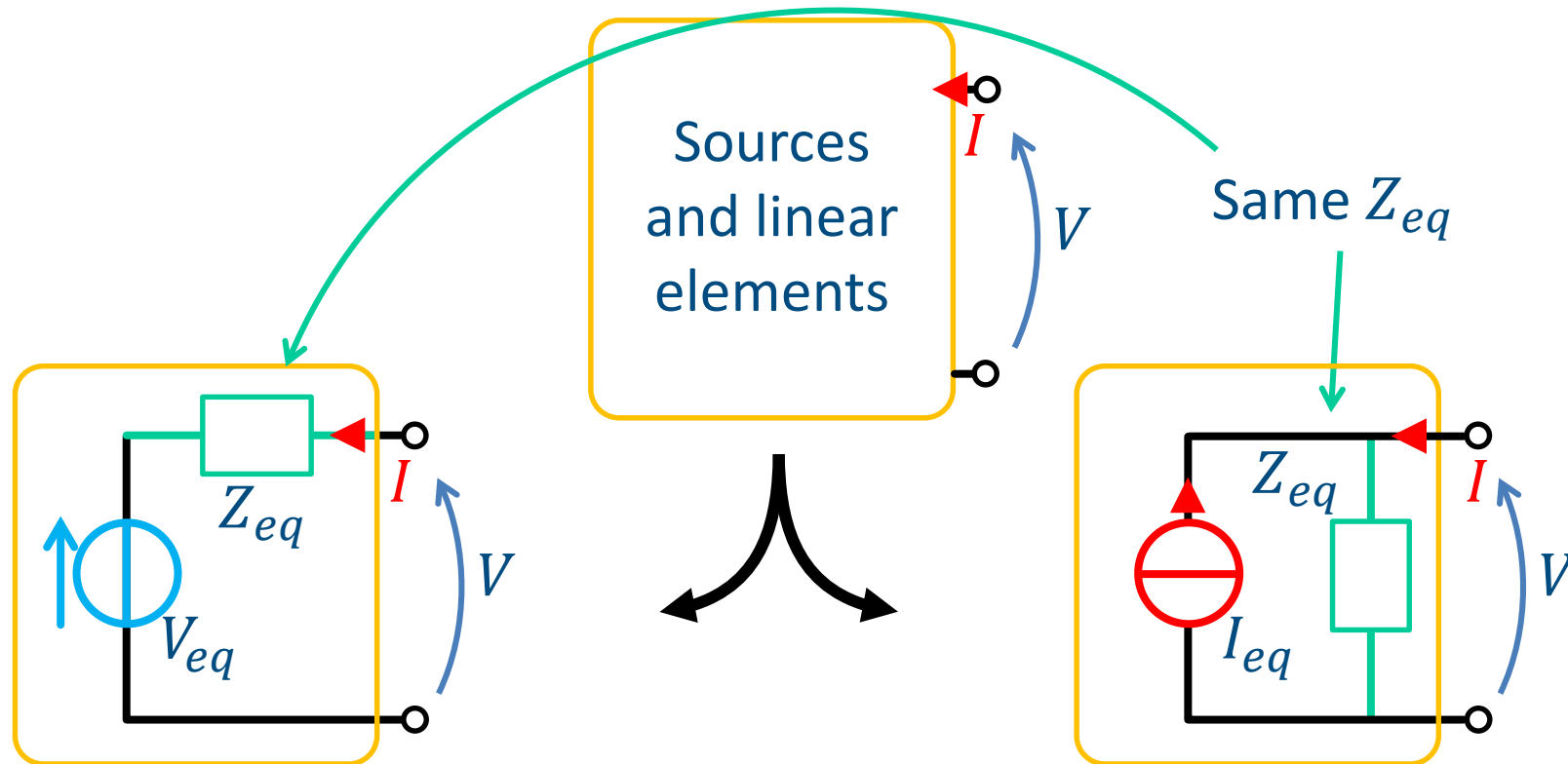
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- Linear network: R, L, C with parameters not dependent on I or V and V/I sources either constant or linearly dependent on other voltages or currents
- Every linear network «seen» between **any** pair of terminals behaves as if composed by a source and an impedance **only**
  - Thévenin equivalent circuit: **voltage** source with impedance in **series**
  - Norton equivalent circuit: **current** source with impedance in **parallel**



# Equivalent circuits

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Equivalence is **only from the viewpoint of the external load.**

Power dissipation, for example, is not equal





- $V_{eq}$  is the open-circuit voltage at the terminals
- $I_{eq}$  is the short-circuit current through the terminals
- $Z_{eq} = V_{eq}/I_{eq}$ , or equivalently
- $Z_{eq}$  is the impedance between the terminals when
  - Independent voltage sources are replaced by short-circuits
  - Independent current sources are replaced by open circuits

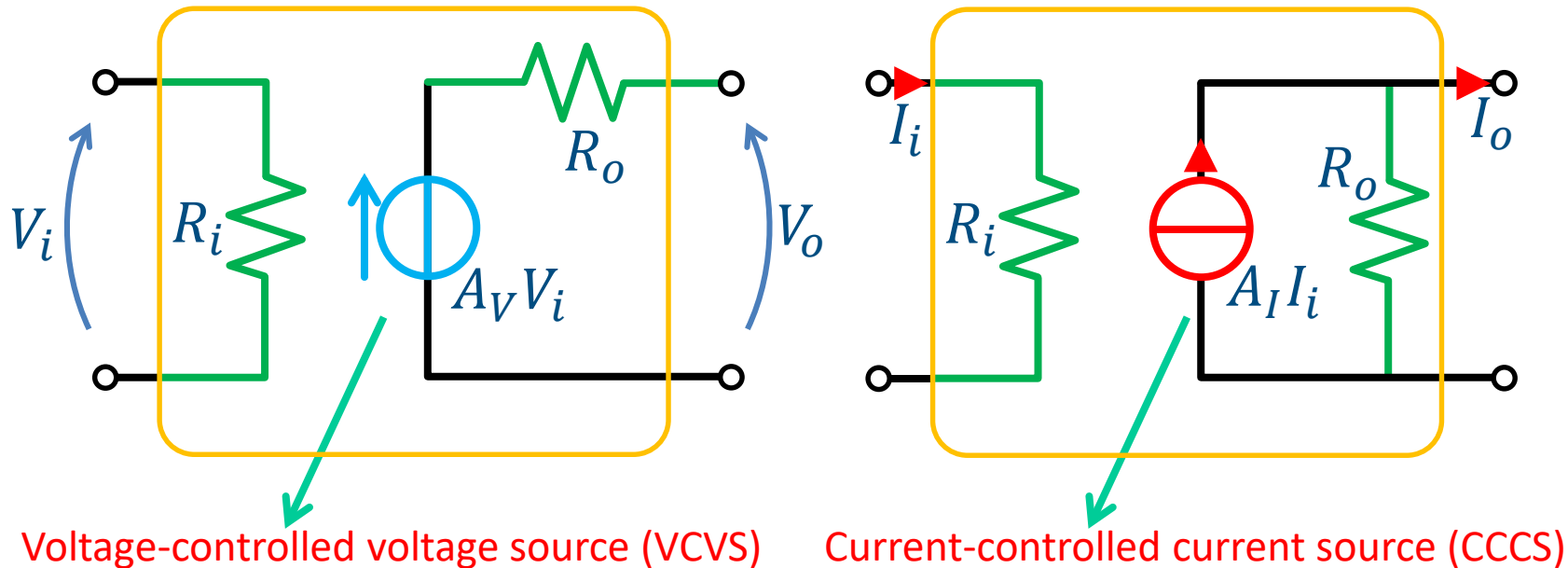


- Review: equivalent circuits
- **Amplifiers**
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- We consider a «black box» approach with equivalent circuits
- Four kinds can be identified:

In	Out	Type
V	V	Voltage ampl.
I	I	Current ampl.
V	I	Transconductance ampl.
I	V	Transresistance ampl.

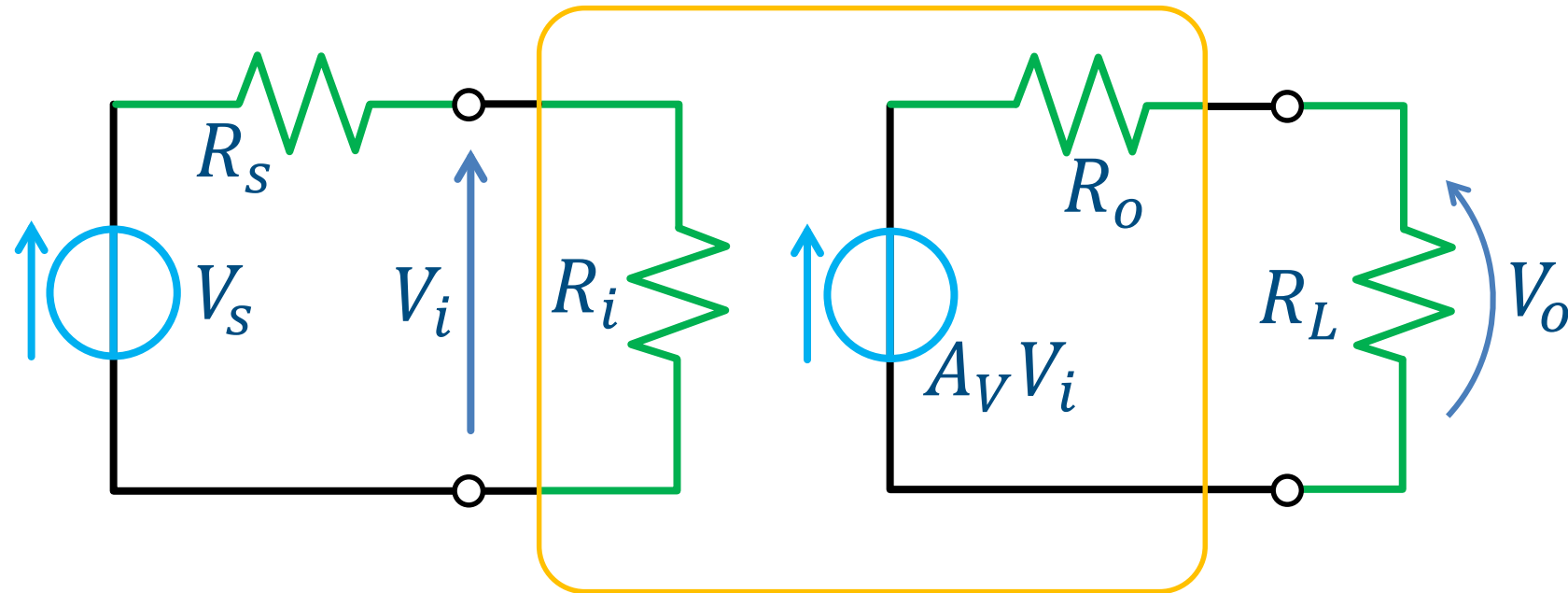


- One-directional amplifiers (no reverse transfer from output to input)
- Resistors will be considered for simplicity, though complex impedances can be assumed



# Source and load resistors (VA)

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$$V_i = V_S \frac{R_i}{R_i + R_S}$$

$$V_O = A_V V_i \frac{R_L}{R_O + R_L}$$



$$\frac{V_o}{V_S} = A_V \frac{R_L}{R_o + R_L} \frac{R_i}{R_i + R_S}$$

- Total gain is less than  $A_V$
- Gain is dependent on  $R_S$  and  $R_L$
- To avoid these drawbacks, a voltage amplifier should have:

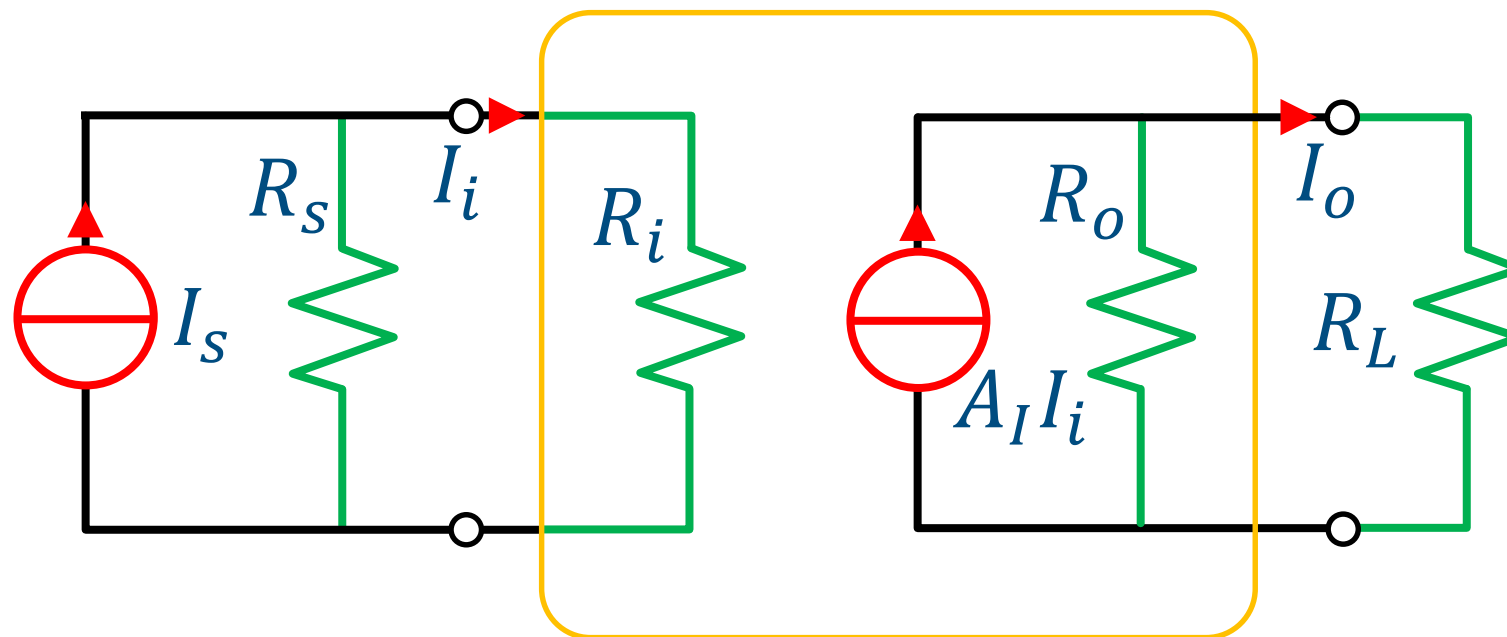
$R_i = \infty$  (very high input impedance)

$R_o = 0$  (very low output impedance)



# Source and load resistors (CA)

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$$I_i = I_S \frac{R_S}{R_i + R_S}$$

$$I_o = A_I I_i \frac{R_O}{R_O + R_L}$$



$$\frac{I_o}{I_S} = A_I \frac{R_o}{R_o + R_L} \frac{R_S}{R_i + R_S}$$

- Total gain is less than  $A_I$
- Gain is dependent on  $R_S$  and  $R_L$
- To avoid these drawbacks a current amplifier should have:

$R_i = 0$  (very low input impedance)

$R_o = \infty$  (very high output impedance)





# Summary

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Type	$R_i$	$R_o$
Voltage amplifier	$\infty$	0
Current amplifier	0	$\infty$
Transconductance ampl.	$\infty$	$\infty$
Transresistance ampl.	0	0



- Review: equivalent circuits
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# American telephone lines...

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- First transcontinental telephone line built in 1914 (announced 1915), upgraded in 1921 to three channels and using twelve amplifiers
- Second line built in 1923 with four channels and twenty amplifiers
- A further increase in the number of channels was very, very challenging...



# The amplifier problem

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- Signal is attenuated as it propagates along the wires and must be regenerated
- Vacuum-tube amplifiers were costly  $\Rightarrow$  minimum number of amplifiers with high gain
- Gain changes with plate voltage, temperature, humidity, aging,...
- Non-linearity creates intermodulation distortion in multi-channel systems

$$\sin \omega t \longrightarrow \boxed{x^2} \longrightarrow \sin^2 \omega t \approx \sin 2\omega t$$



# Negative-feedback concept

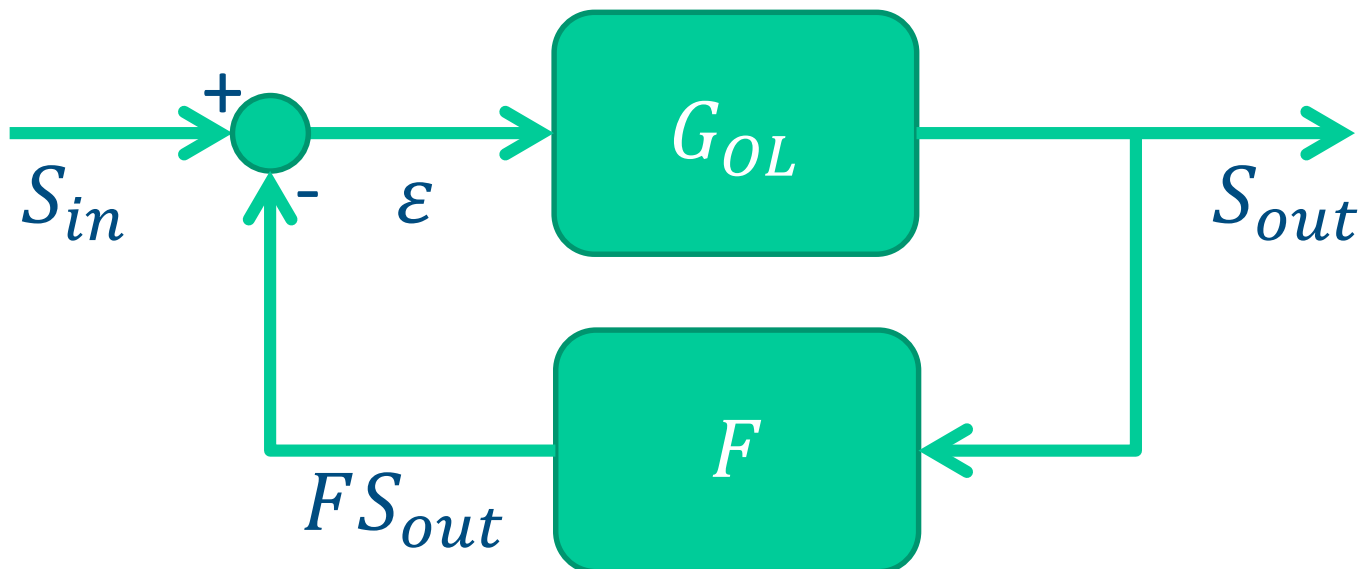
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Harold S. Black (1898-1983)



From [2]



$$\begin{aligned}\varepsilon &= S_{in} - F S_{out} \\ S_{out} &= G_{OL} \varepsilon\end{aligned}$$

$$\frac{S_{out}}{S_{in}} = G = \frac{G_{OL}}{1 + G_{OL}F}$$



# Closed-loop gain

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$$|G_{OL}F| \ll 1 \rightarrow G = \frac{G_{OL}}{1 + G_{OL}F} \sim G_{OL}$$

Open-loop gain, no  
feedback

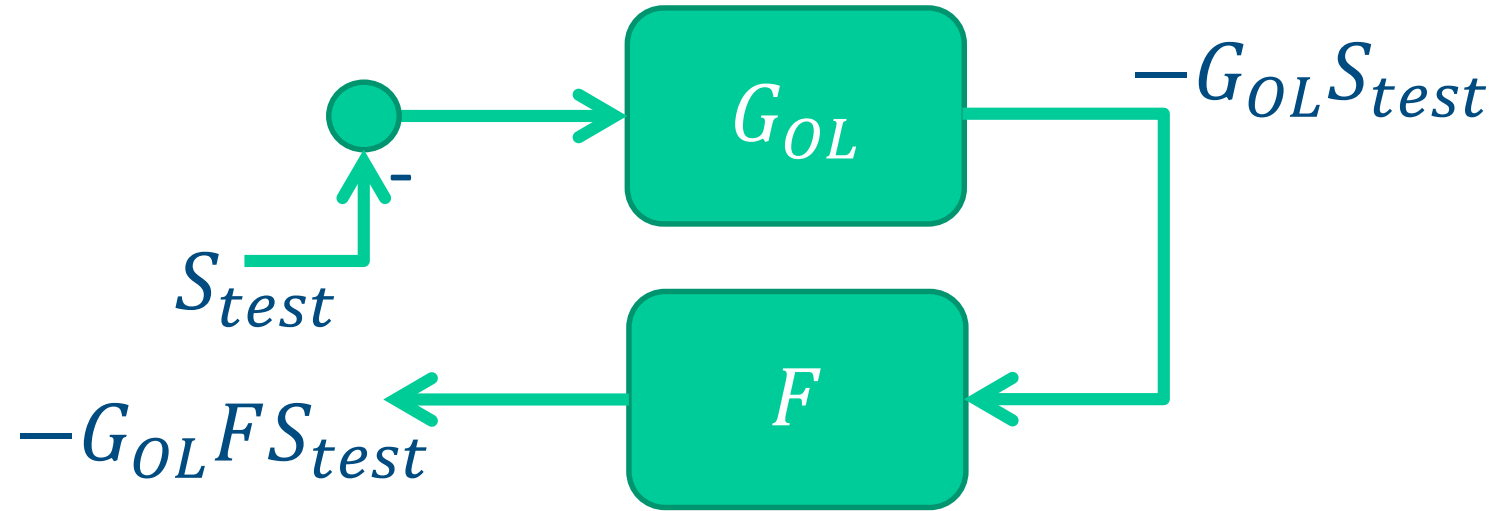
$$|G_{OL}F| \gg 1 \rightarrow G = \frac{G_{OL}}{1 + G_{OL}F} \sim \frac{1}{F} = G_{id}$$

Ideal gain,  
independent of  $G_{OL}$



# Loop gain – calculation

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- $G_{loop} = -G_{OL}F$  measures the strength of the feedback
- The result is independent of the breaking point
- A good feedback system has  $G_{loop} < 0$  and  $|G_{loop}| \gg 1$





$$G = \frac{G_{OL}}{1 + G_{OL}F} = \frac{1/F}{1 + 1/G_{OL}F} = \frac{G_{id}}{1 - 1/G_{loop}}$$

- Example:

$$G_{OL} = 10^5, F = 10^{-2}$$

$$\Rightarrow G_{loop} = -1000, G_{id} = 100, G = 99.9$$

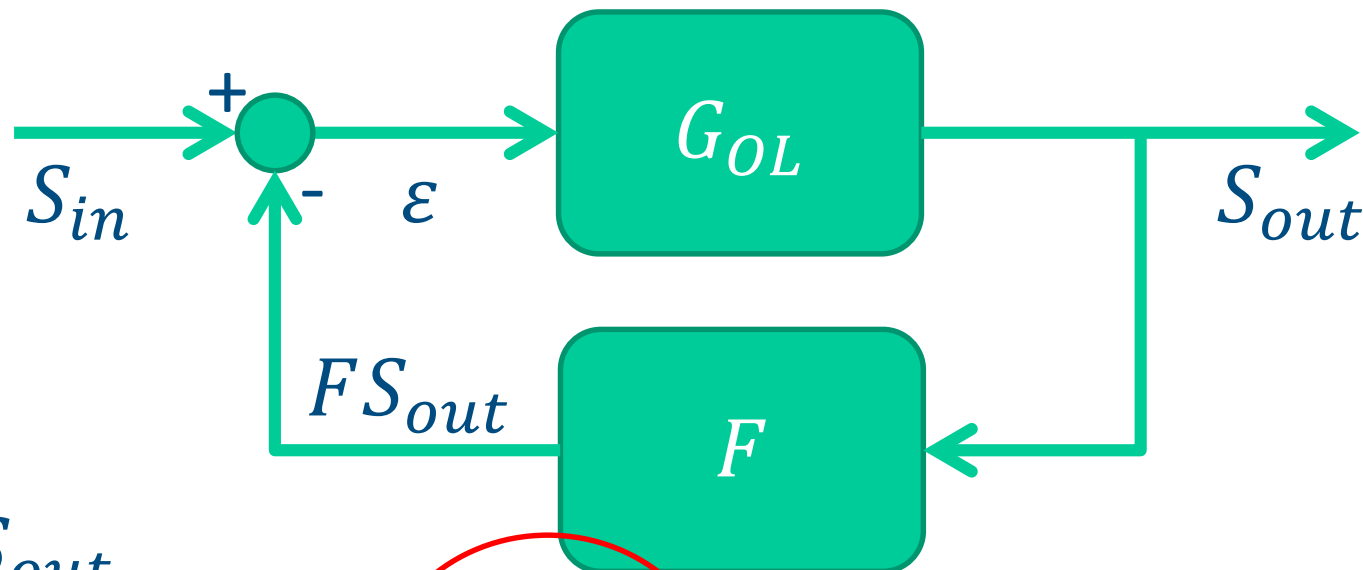
- The **relative error** between  $G$  and  $G_{id}$  is

$$\varepsilon_{rel} = \frac{G_{id} - G}{G_{id}} = \frac{100 - 99.9}{100} = 0.001 = \frac{1}{|G_{loop}|}$$



# Error signal

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$$\varepsilon = S_{in} - FS_{out}$$

$$\frac{\varepsilon}{S_{in}} = 1 - FG = \frac{\frac{G_{id} - G}{G_{id}}}{1 - \frac{1}{G_{loop}}} = \frac{1}{1 - G_{loop}} \sim \frac{1}{|G_{loop}|}$$



# Sensitivity to $G_{OL}$

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$$\frac{dG}{dG_{OL}} = \frac{1}{(1 + G_{OL}F)^2} = \frac{G}{G_{OL}} \frac{1}{1 - G_{loop}}$$

$$\frac{dG}{G} = \frac{dG_{OL}}{G_{OL}} \frac{1}{1 - G_{loop}} \ll 1$$

$$G_{OL} = 10^5, F = 0.01 \quad \Rightarrow \quad G = 99.9$$

$$G_{OL} = 2 \times 10^5, F = 0.01 \quad \Rightarrow \quad G = 99.95$$



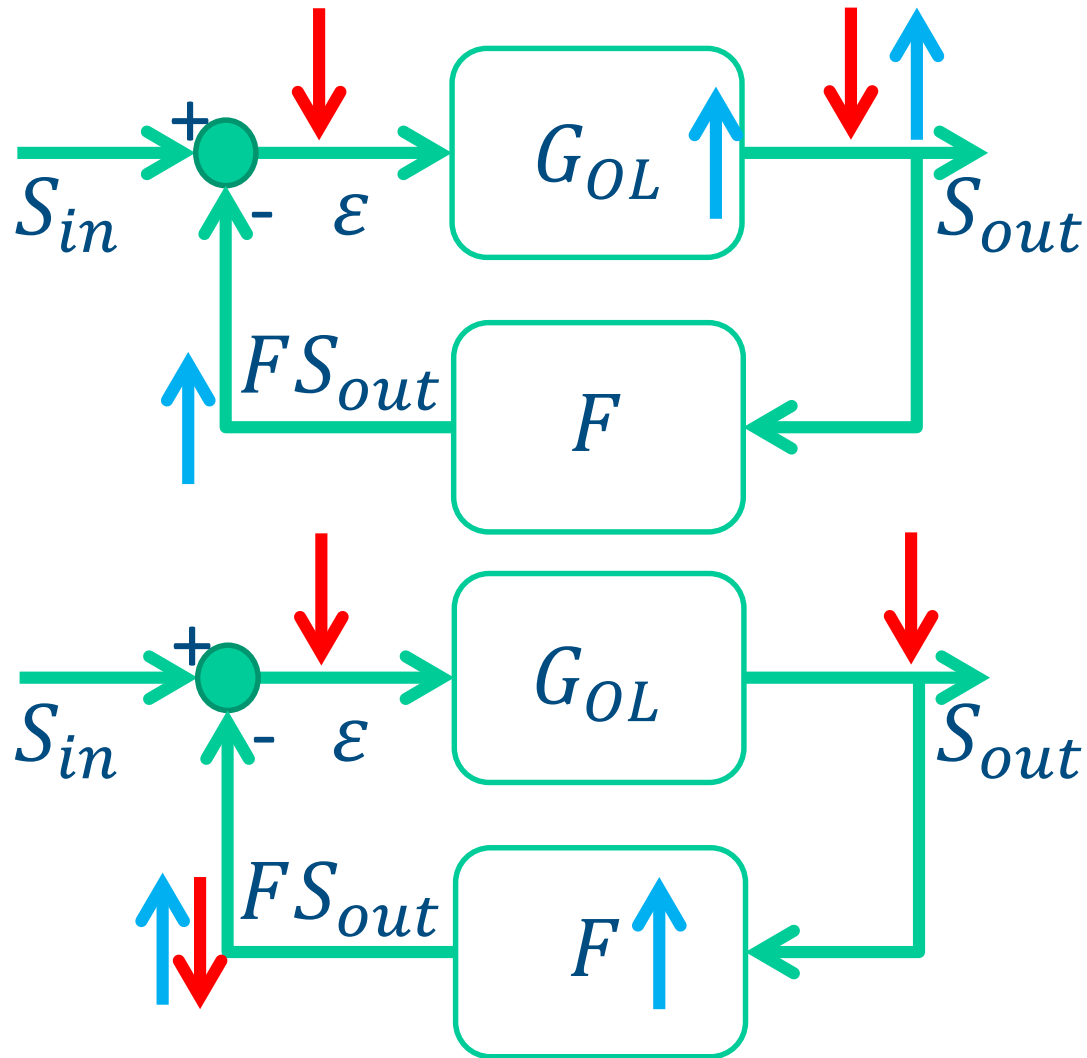
$$\frac{dG}{dF} = -\frac{G_{OL}^2}{(1 + G_{OL}F)^2} = -G^2$$
$$\frac{dG}{G} = \frac{dF}{F} \frac{G_{loop}}{1 - G_{loop}} \approx -1$$

$$G_{OL} = 10^5, F = 0.01 \quad \Rightarrow \quad G = 99.9$$
$$G_{OL} = 10^5, F = 2 \times 0.01 \quad \Rightarrow \quad G = 49.98$$



# Qualitative interpretation

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- Changes in  $G_{OL}$  are nulled by the feedback loop
- Changes in  $F$  cannot be compensated



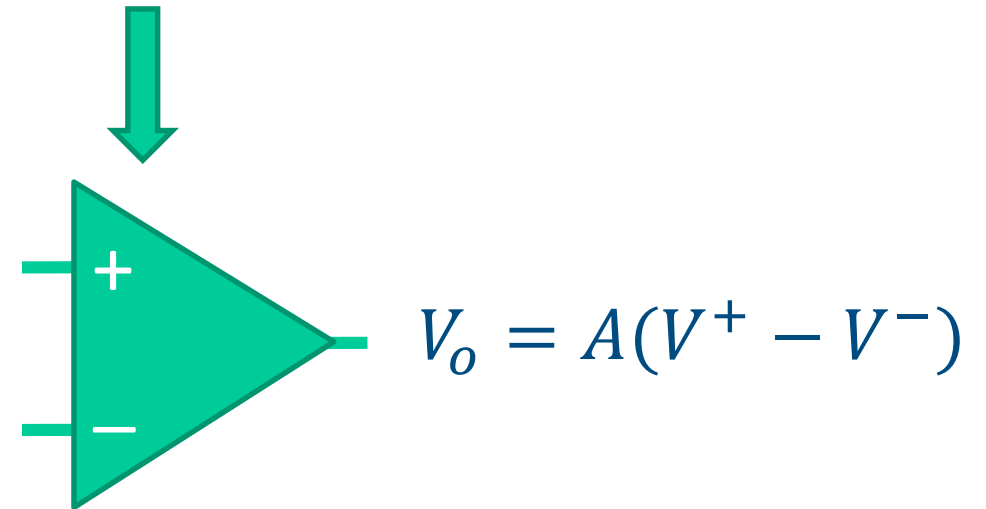
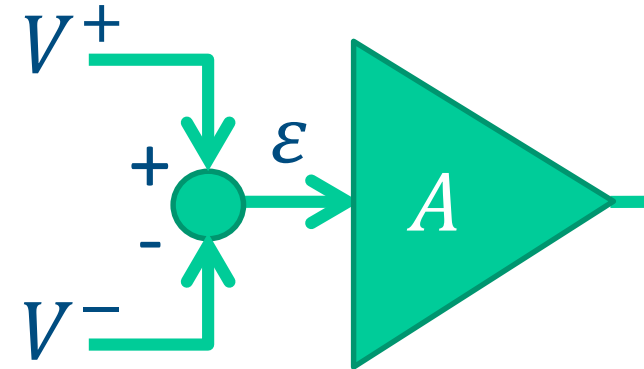
- Forward (open-loop) block  $G_{OL}$  must have **high gain**, to ensure that  $|G_{loop}| \gg 1$ .  
All active elements are placed here even if gain is not stable – their fluctuations are reduced by  $1/|G_{loop}|$
- Feedback block  $F$  must be **stable**, to ensure a stable closed-loop gain  $\Rightarrow$  usually made with passives



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- Integrated voltage amplifiers used as forward gain blocks in feedback circuits
- The ideal OA has
  - $A = \infty$  ( $10^5 - 10^6$ )
  - $R_i = \infty$  ( $10^6 - 10^9 \Omega$ )
  - $R_o = 0$  ( $\approx 100 \Omega$ )



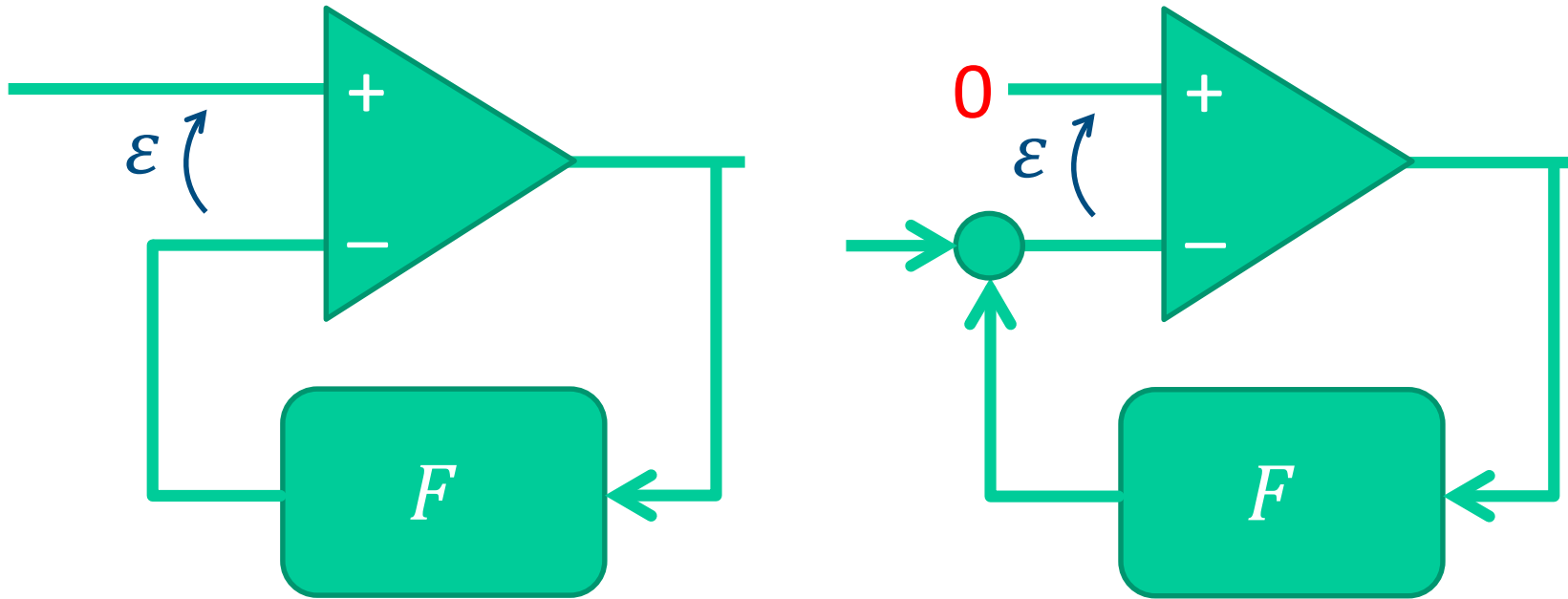




# Typical circuit arrangements

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Feedback  
loop is on the  
negative pin



In ideal feedback loops,  $\varepsilon = 0 \Rightarrow$  ideal OAs keep  $V^+ - V^- = 0$   
 $\Rightarrow V^+ = V^-$



1. <http://tcts.fpms.ac.be/cours/1005-01/equiv.pdf>
2. <https://www.wpi.edu/News/Transformations/2005Summer/tim-ecapsule.html>